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Nonadiabatic quantum control of quantum dot arrays with fixed exchange using Cartan decomposition

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In semiconductor spin qubits which typically interact through short-range exchange coupling, shuttling of spin is a practical way to generate quantum operations between distant qubits. Although the exchange is often tunable through voltages applied to gate electrodes, its minimal value can be significantly large, which hinders the applicability of existing shuttling protocols to such devices, requiring a different approach. In this work, we extend our previous results for double- and triple-dot systems, and describe a method for implementing spin shuttling in long chains of quantum dots in a nonadiabatic manner. We make use of Cartan decomposition to break down the interacting problem into simpler problems in a systematic way, and use dynamical invariants to design smooth nonadiabatic pulses that can be implemented in devices with modest control bandwidth. Finally, we discuss the extensibility of our results to directed shuttling of spin states on two-dimensional lattices of quantum dots with fixed coupling.

I. INTRODUCTION

Spins confined in semiconductor quantum dots are a promising platform for the realization of a useful quantum computer. One-qubit gate fidelities around 99.9% fidelities are routinely achieved in Si/SiO₂ [1, 2] and Si/SiGe heterostructures [3], and two-qubit gate fidelities nearing 99% for entangling neighboring qubits via Heisenberg exchange interaction have recently been reported in [4]. Entangling qubits that are separated over long-distances can be achieved via spin-photon coupling [5–9] by coupling the dots to a common microwave cavity and selectively bringing the qubits in and out of resonance. For intermediate length scales, coherent shuttling of spins via adiabatic passage [10, 11] or through repeated SWAP operations [12] is a viable route to entangle distant qubits, which can be achieved by modulating the voltages applied to the gate electrodes without the overhead of a resonator.

Heisenberg exchange interaction can allow direct implementation of SWAP gates, provided that it can be turned on and off between the neighboring quantum dots. However, when there is a large variation in energy splitting between adjacent qubits, the Heisenberg coupling effectively reduces to an Ising ZZ coupling in the rotating wave approximation, thus preventing the direct swapping of spins without application of local driving fields. Furthermore, in devices with an always-on exchange coupling [13], implementation of any quantum gate can be a challenge due to crosstalk [13]. Nonetheless, in certain scenarios, such systems with high connectivity can be systematically broken into a simpler set of noninteracting subsystems (which may however share control degrees of freedom) by means of Cartan decomposition [14], as exemplified in [15–17] in quantum double dots and in [18] for triple dots. However, these methods are not readily applicable to networks of quantum dots with larger number of spins, or topologies beyond a one-dimensional

chain.

In this paper, we extend the earlier works to arbitrary long chains (> 3) of quantum dots with always-on couplings, and present a method of achieving spin-shuttling in a nonadiabatic manner using Cartan decomposition, by using iSWAP as the primitive. We also discuss how these results might be extended to two-dimensional lattices. This paper is organized as follows. We first give a brief review of Cartan decomposition in the context of dynamical invariants. In Sec. III that follows, a model describing a chain of singly loaded quantum dots that is driven by an ESR line is given, operating in a regime that is specified. Sec. IV starts by showing how to build the iSWAP out of these components. Then it continues by showing how to create the elementary gates of the iSWAP gate using square pulse sequences. Finally, in Sec. V the individual gates are partially implemented using smooth pulses with modest bandwidth requirements, by parameterizing the problem using dynamical invariants.

II. CARTAN DECOMPOSITION AND DYNAMICAL INVARIANTS

A dynamical invariant $I(t)$ is an operator whose expectation value is conserved, and obeys the defining equation

$$i\partial_t I(t) = [H(t), I(t)] \quad (1)$$

where $H(t) \in \mathfrak{su}(N)$ is the Hamiltonian of the system. It allows expressing the time-evolution operator as

$$U(t; 0) = \sum_n e^{i\alpha_n(t)} \sum_i |\phi_n(t)\rangle \langle \phi_n(0)|, \quad (2)$$

$$\alpha_n(t) = \int_0^t ds \langle \phi_n(s) | (i\partial_s - H(s)) | \phi_n(s) \rangle \quad (3)$$

where $|\phi_n(t)\rangle$ are the instantaneous eigenvectors of $I(t)$ and $\alpha_n(t)$ are the associated Lewis-Riesenfeld phases [19].

The eigenvalues of $I(t)$ are constants in time. One useful aspect of dynamical invariants is that they provide a set of states that are transitionless, such that if the system is initialized to $|\phi_m(0)\rangle$, it will later evolve into $e^{i\alpha_m(t)}|\phi_m(t)\rangle$. This form is similar to that of adiabatic evolution of the eigenvectors of $H(t)$, except it is valid in the nonadiabatic regime as well [20]. The two terms in the Lewis-Riesenfeld phase can be recognized as the geometric and dynamical phase, which makes the dynamical invariant a natural parametrization to study geometric quantum gates [21–23].

$$[\mathfrak{k}, \mathfrak{k}] \subseteq \mathfrak{k}, \quad [\mathfrak{k}, \mathfrak{p}] \subseteq \mathfrak{p}, \quad [\mathfrak{p}, \mathfrak{p}] \subseteq \mathfrak{k}. \quad (4)$$

These relations have a direct implication on Eq. (1): the dynamical invariant can be chosen to be in the same sub-

algebra \mathfrak{k} as $H(t)$, or in the vector space \mathfrak{p} [14], where the possible choices for \mathfrak{k} are determined by the maximal subalgebras of the Lie algebra $\mathfrak{su}(N)$.

The minimal interesting example is the case of two-qubits for which $N = 4$, whose maximal subalgebras are tabulated in Table II. As we will show in the next section, a pair of spin qubits in a double quantum dot can be described using the following rotating frame Hamiltonian,

$$H = \frac{J}{4} Z_1 Z_2 + \sum_{i=1}^2 \frac{\Omega_i}{2} (\cos(\phi_i) X_i + \sin(\phi_i) Y_i), \quad (5)$$

where $\sigma_{Z,i}$ is the Z Pauli operator on the i -th qubit, J is the strength of the exchange coupling, and Ω_i, ϕ_i are the amplitude and phase of the drive. When the qubits are driven one at a time, say $\Omega_2 = 0$ for concreteness, the Hamiltonian fits into the $\mathfrak{su}(2) \oplus \mathfrak{su}(2) \oplus \mathfrak{u}(1)$ with the Cartan decomposition

$$\begin{aligned} \mathfrak{su}(4) = \text{span} \left(\left\{ X_1 \frac{1+Z_2}{2}, Y_1 \frac{1+Z_2}{2}, Z_1 \frac{1+Z_2}{2} \right\} \sqcup \left\{ X_1 \frac{1-Z_2}{2}, Y_1 \frac{1-Z_2}{2}, Z_1 \frac{1-Z_2}{2} \right\} \sqcup \underbrace{\{Z_2\}}_Q \right) \\ \sqcup \underbrace{\{X_1 Y_2, Y_1 Y_2, Z_1 Y_2, X_2\}}_P \sqcup \underbrace{\{X_1 X_2, Y_1 X_2, Z_1 X_2, -Y_2\}}_P. \end{aligned} \quad (6)$$

$\mathfrak{su}(3) \oplus \mathfrak{u}(1)$	$8_0 + 1_0 + 3_{-4} + \bar{3}_4$
$\mathfrak{su}(2) \oplus \mathfrak{su}(2)$	$(3, 1) + (1, 3) + (3, 3)$
$\mathfrak{su}(2) \oplus \mathfrak{su}(2) \oplus \mathfrak{u}(1)$	$(3, 1)_0 + (1, 3)_0 + (1, 1)_0 + (2, 2)_2 + (2, 2)_{-2}$
$\mathfrak{so}(5)$	$10 + 5$

TABLE I. Maximal subalgebras of $\mathfrak{su}(4)$ [24] and the corresponding partitioning of the 15-dimensional vector space in the adjoint representation. \mathfrak{p} is partitioned into two in the presence of a $\mathfrak{u}(1)$.

We remark that P and \bar{P} are related to each other by an infinitesimal $\mathfrak{u}(1)$ “charge conjugation” [14]

$$[Q, P] = -2i\bar{P}, \quad [Q, \bar{P}] = 2iP. \quad (7)$$

Since $\mathfrak{su}(2) \oplus \mathfrak{su}(2)$ does not mix P and \bar{P} under commutation, when the Hamiltonian is missing the $\mathfrak{u}(1)$ term, it becomes possible to choose a dynamical invariant in span of P or \bar{P} . As a result, in the 15-dimensional real adjoint representation, the Hamiltonian becomes block diagonal with the structure $3 + 3 + 1 + 4 + 4$ [14]. Similar arguments can be made for the density matrix $\rho(t)$ which also obeys the same equation as a dynamical invariant, although differs from $I(t)$ by an unimportant (in this context) term that is proportional to identity matrix as required by the trace condition $\text{Tr}(\rho) = 1$.

III. MODEL

A chain of N nearest-neighbor exchange coupled silicon quantum dots in the presence of magnetic fields is well known to be described by the Heisenberg model Hamiltonian [25]

$$H = \sum_{i=1}^{N-1} J_{i,i+1} \left(\mathbf{S}_i \cdot \mathbf{S}_{i+1} - \frac{1}{4} \right) + \sum_{i=1}^N \mu g_i \mathbf{B}_i \cdot \mathbf{S}_i \quad (8)$$

where $J_{i,i+1}$ is the exchange strength between neighboring dots, \mathbf{S}_i is the spin operator of the i -th qubit, μ is the Bohr magneton, g_i is the g -factor of the i -th qubit and \mathbf{B}_i is the magnetic field at the i -th qubit. The exchange coupling in this paper is taken to be fixed, always-on, and the same between each qubit meaning $J_{i,i+1} = J$. Additionally, in this work the magnetic field is applied only in the Z and X -directions and will now be described by the Zeeman energy $E_{z,i} = \mu g_i B_{z,i}$ for the Z -direction and the envelope, Ω_i , frequency, ω_i , and phase ϕ_i , $\Omega_i \cos(\omega_i t + \phi_i) = \mu g_i B_{x,i}$ for the X -direction. The Zeeman energies are taken to be large and constant with the differences between Zeeman energies of neighboring qubits being large compared to the other terms in the Hamiltonian as is often the case in experiment [26]. To avoid the large Zeeman energies, the Hamiltonian in (8) is moved to the rotating frame $R = e^{\frac{i}{2} \sum_{i=1}^N E_{z,i} t \sigma_z^{(i)}}$. As a result of the large difference in

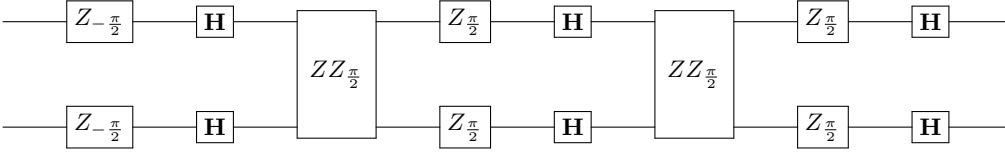


FIG. 2. Circuit diagram of the gates which result in an iSWAP gate between two qubits. \mathbf{H} and A_θ respectively denote a Hadamard gate and a θ rotation around A .

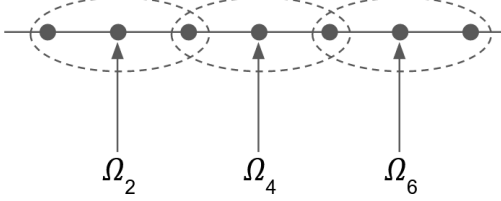


FIG. 1. Schematic representation of the driving on a chain of qubits which results in $(N - 1)$ $\mathfrak{su}(2)$ s. The dashed circle indicate the qubits involved in the separate $\mathfrak{su}(2)$ s.

Zeeman energies it is possible to apply the rotating wave approximation to the Hamiltonian in the rotating frame $H_R = RHR^\dagger + i\hbar(\partial_t R)R^\dagger$ which results in:

$$H_{R,N} \approx \sum_{i=1}^{N-1} \frac{J}{4} Z_i Z_{i+1} + \sum_{i=1}^N \frac{\Omega_i}{2} (\cos(\phi_i) X_i + \sin(\phi_i) Y_i) \quad (9)$$

If in Eq. (9) every other qubit is locally driven, i.e., $\Omega_i = 0$ for even or odd i as represented schematically in Fig.1, then there exists a decomposition of the Hamiltonian in terms of $N - 1$ $\mathfrak{su}(2)$ s and $N - 1$ $\mathfrak{u}(1)$ s within this $\mathfrak{su}(2^N)$ algebra. This can be shown by examining a three qubit string within this Hamiltonian such as $H_{R,3}$ with $\Omega_i = \Omega(t)\delta_{i,2}$.

$$H_{R,3} = \frac{J}{4} (Z_1 Z_2 + Z_2 Z_3) + \frac{\Omega(t)}{2} (\cos(\phi(t)) X_2 + \sin(\phi(t)) Y_2) \quad (10)$$

In Fig. 2 the individual Hadamard gates are not performed simultaneously because this approach relies on the decomposition of the Hamiltonian into $\mathfrak{su}(2)$ s which does not work when driving neighboring qubits simultaneously. There are a total of six Hadamard gates and two $\frac{\pi}{2}$ ZZ rotations, which we will show below takes a total time of $t_{\text{iSWAP}} \approx 116/J$ using square pulses.

As was shown in Ref. [18, 27] this Hamiltonian can be decomposed into four possible $\mathfrak{su}(2)$ $H_{\pm,\pm}$

$$H_{R,3} = H_{++} + H_{+-} + H_{-+} + H_{--} \quad (11)$$

where, taking the phases of the driving $\phi_i = 0$,

$$H_{++} = \frac{J}{2} Z_{++} + \frac{\Omega}{2} X_{++} \quad (12)$$

$$H_{+-} = -\frac{\Omega}{2} X_{+-} \quad (13)$$

$$H_{-+} = -\frac{\Omega}{2} X_{-+} \quad (14)$$

$$H_{--} = -\frac{J}{2} Z_{--} + \frac{\Omega}{2} X_{--} \quad (15)$$

and

$$Z_{s_1 s_2} = \frac{1}{4} (Z_1 + s_1 I) Z_2 (Z_3 + s_2 I) \quad (16)$$

$$X_{s_1 s_2} = \frac{1}{4} (Z_1 + s_1 I) X_2 (Z_3 + s_2 I), \quad (17)$$

with $s_i \in \{+, -\}$. H_{+-} and H_{-+} in Eqs. (13) and (14) have been further simplified to $\mathfrak{u}(1)$ s as a result of choosing $J_{i,i+1} = J$.

IV. SEQUENCE FOR DOING AN ISWAP GATE USING SQUARE PULSES

A. Composition of an iSWAP gate

An iSWAP gate can be created from Hadamard gates, Z rotations and $\frac{\pi}{2}$ ZZ rotations using the scheme designed with methods from Ref. [28, 29] and shown in Figure 2. The Z rotations will be done virtually [30], the Hadamard will be performed by virtual Z -gates and a $\frac{\pi}{2}$ X rotation and the ZZ rotations will be performed using a sequence of X gates and turned off driving.

B. Individual gates

Within an $\text{SU}(2)$ it is possible to do any rotation using the Euler angle decomposition which only requires rotations around two perpendicular axes. This is possible for the $\text{SU}(2)$ s generated from Eq. (12) and (15) by applying $\Omega = \pm J$ in alternating fashion. For the $\mathfrak{su}(2)$'s that simplify into $\mathfrak{u}(1)$'s in Eq. (13)-(14) it is only possible to

do one type of rotation, however we will show that this is sufficient for doing an iSWAP gate.

1. $\frac{\pi}{2}$ X rotation concurrently with identities in other subspaces

The Pauli X operator on the second qubit is equivalent to an equally weighted sum of $X_{s_1 s_2}$ generators,

$$X_2 = (X_{++} - X_{+-} - X_{-+} + X_{--}). \quad (18)$$

This means a $\frac{\pi}{2}$ rotation around X on the second qubit is equivalent to performing an $s_1 s_2 \frac{\pi}{2}$ rotation around each of the $X_{s_1 s_2}$ generators. The $++$ and $--$ Hamiltonians are symmetric, therefore the X_{++} and X_{--} rotations can be achieved at the same time. The desired $\frac{\pi}{2}$ X_{++} and X_{--} rotations are created with a pulse sequence which implements the Euler decomposition by switching Ω between $\pm J$ and using

$$\begin{aligned} e^{-i\frac{Jt_1}{2}(Z_{+++}+X_{+++})} e^{-i\frac{Jt_2}{2}(Z_{++-}-X_{+++})} \\ e^{-i\frac{Jt_3}{2}(Z_{+++}+X_{+++})} = e^{-i\frac{\pi}{4}X_{++}}. \end{aligned} \quad (19)$$

The solution with the minimum elapsed time is

$$t_1 = t_3 = \frac{\arctan(1/\sqrt{2})}{\sqrt{2}J}, \quad (20)$$

$$t_2 = \frac{5\sqrt{2}\pi}{3J} \quad (21)$$

At the same time evolution in the $+-$ and $-+$ subspaces also happens, but this is not generally equivalent to the intended $-\frac{\pi}{2}$ rotation. To create the desired $-\frac{\pi}{2}$ rotation in these subspaces a final step is added to the sequence. This step ensures that the pulse area under $\Omega(t)$ for the entire sequence is equivalent to a $-\frac{\pi}{2}$ in the $+-$ and $-+$ spaced. Additionally, the rotation in the $++$ and $--$ subspaces is preserved by producing an identity up to π Z_1 and Z_3 rotations, which can be compensated virtually through the phase degree of freedom[30, 31]. These conditions can be expressed as

$$\frac{J}{2}(t_1 - t_2 + t_3) + \frac{\Omega}{2}t_4 = 2m\pi + \frac{\pi}{4}, \quad (22)$$

$$t_4 \sqrt{\left(\frac{J}{2}\right)^2 + \left(\frac{\Omega}{2}\right)^2} = n\pi. \quad (23)$$

for any integers n and m . Then the solution for the length and drive amplitude of the final time step that gives a real solution in this case is

$$\Omega = \frac{J(\pi - 2J\tau)}{\sqrt{(9\pi - 2J\tau)(7\pi + 2J\tau)}} \approx 0.991J, \quad (24)$$

$$t_4 = \frac{\sqrt{(9\pi - 2J\tau)(7\pi + 2J\tau)}}{2J} \approx 8.926/J, \quad (25)$$

where $\tau = t_1 - t_2 + t_3$. The total time of the X rotation is $t_{\frac{\pi}{2}X} \approx 17.94/J$. For a chain of N qubits it is also necessary to create identities in this structure of $\mathfrak{su}(2)$ s on all other qubits at the same time. This can be achieved by a two part pulse in which $\Omega_1 = -\Omega_2$ such that the $+-$ and $-+$ spaces create an identity. The identity in the $++$ and $--$ spaces is found by driving at strength $\Omega = 2\sqrt{(2n\pi/t)^2 - (\frac{J}{2})^2}$ for any pulse time t and integer n that gives a real solution. Additionally, any necessary virtual Z rotations can be done during any of the X rotations sequences mentioned in this section by adjusting the phase, ϕ_i ,

$$e^{-i\theta(\cos(\phi_i)X_i + \sin(\phi_i)Y_i)} = e^{-i\frac{\phi_i}{2}Z_i} e^{-i\theta X_i} e^{i\frac{\phi_i}{2}Z_i}. \quad (26)$$

2. Hadamard gates and virtual Z rotation

It is possible to create a Hadamard gate, \mathbf{H} , up to a global phase by doing a combination of a $\frac{\pi}{2}$ X rotation and two Z rotations,

$$\mathbf{H}_i = e^{-i\frac{\pi}{4}Z_i} e^{-i\frac{\pi}{4}X_i} e^{-i\frac{\pi}{4}Z_i}. \quad (27)$$

At this point we note that for spin shuttling in this scheme only X rotations, ZZ rotations and Z rotations are necessary and because ZZ rotations commute with the Z rotations it will always be possible to resolve the necessary Z rotations using virtual- Z rotations generated during the X rotations.

3. $\frac{\pi}{2}$ ZZ rotation concurrently with identities in other subspaces

The $Z_1 Z_2$ operator is equivalent to a weighted sum of $Z_{s_1 s_2}$,

$$Z_1 Z_2 = (Z_{++} + Z_{+-} - Z_{-+} - Z_{--}). \quad (28)$$

From the Hamiltonians in Eq. (13) and (14) it is apparent that this cannot be directly created since the Z_{-+} and Z_{+-} generators are absent. It is, however, possible to acquire a phase on the $Z_1 Z_2 + Z_2 Z_3$ term in the exponential by simply turning off the Ω driving for a time $\pi/2J$, then performing an X_3 gate, then repeating those two steps to echo out the $Z_2 Z_3$ term and produce the desired gate, $\exp(-i\pi/4 Z_1 Z_2)$. This echo works because X_3 commutes with $Z_1 Z_2$ and anticommutes with $Z_2 Z_3$. For a larger chain it is necessary to do identities in all other subspaces at the same time, which is possible by using the same trick mentioned at the end of Sec. IVIV BIV B 1 with the time being $t_{ZZ} = \pi/J$.

The X gates required to produce the $\frac{\pi}{2}$ ZZ rotation can be composed of two $\frac{\pi}{2}$ X rotations as mentioned in Sec. IVIV BIV B 1. However, this rotation can be performed faster by using the four-step process of Sec. IVIV BIV B 1 for a π X rotation directly. Using

$\tau = t_1 - t_2 + t_3$ the shortest real solutions for an X gate if found with the times and qubit driving strengths

$$t_1 = t_3 = \frac{\pi}{2\sqrt{2}J}, \quad (29)$$

$$t_2 = \frac{7\pi}{2\sqrt{2}J}, \quad (30)$$

$$t_4 = \frac{\sqrt{(5\pi - J\tau)(3\pi + J\tau)}}{J} \approx 9.07233/J, \quad (31)$$

$$\Omega_1 = \Omega_3 = -\Omega_2 = J, \quad (32)$$

$$\Omega_4 = \frac{J(\pi - J\tau)}{\sqrt{(5\pi + J\tau)(3\pi + J\tau)}} \approx 0.95843J. \quad (33)$$

This results in the total evolution operator, $U = \prod_{j=1}^4 e^{it_j(\frac{J}{4}(Z_1Z_2+Z_2Z_3)+\Omega_jX_2)}$, being equivalent to an X gate up to a global phase. The time for this X gate is $t_{\pi X} \approx 19.07/J$, which is almost twice as fast as two $\frac{\pi}{2}$ X rotations. This makes the combined time for the $\frac{\pi}{2}$ ZZ rotation to $\approx 41.28/J$.

However, in the context of the overall circuit of Fig. 2, instead of echoing away Z_2Z_3 within each of the entangling segments of the circuit (which requires four X_3 gates in total), we can save time by just performing an X_3 after each $\pi/2$ ZZ rotation of Fig. 2. Since qubits that are not nearest neighbors can safely be driven simultaneously without ruining the $\mathfrak{su}(2)$ decomposition of the Hamiltonian, the X_3 gate can be done at the same time as the trailing Hadamards on qubit 1, as long as the difference in times is accounted for with an additional identity on qubit 1 to pad the time as discussed in Sec. IVIVBIVB1. Thus, the entire circuit requires six $\frac{\pi}{2}$ X rotations and two π X rotations in addition to the instantaneous virtual Z rotations and the two $\pi/2$ ZZ rotations, and accounting for the fact that gates on nearest neighbors cannot be performed in parallel, the total time for the iSWAP using the above square pulses is $t_{\text{iSWAP}} = 4t_{\frac{\pi}{2}X} + 2t_{\pi X} + 2\pi/J \approx 116/J$.

4. Rotations on edge qubits

As an aside, we note that in the case where the driving is on a qubit at an end of the linear array, the decomposition mentioned above is not necessary because the Hamiltonian already has the $\mathfrak{su}(2)$ structure

$$H_{\text{edge}} = \frac{J}{4}Z_1Z_2 + \frac{\Omega(t)}{2}(\cos(\phi(t))X_1 + \sin(\phi(t))Y_1). \quad (34)$$

Using H_{edge} it is possible to do a $\frac{\pi}{2}$ ZZ rotation by simply waiting time $t = \pi/(4J)$. An identity is always possible by driving at strengths $\Omega = 2\sqrt{(2n\pi/t)^2 - (J/4)^2}$ for any integer n which yields a real result. Finally, a $\frac{\pi}{2}$ X rotation is possible by using an Euler angle decomposition

using $\Omega_1 = \Omega_3 = -\Omega_2 = J/2$ with

$$t_1 = t_3 = \frac{\sqrt{2} \arctan(\sqrt{2})}{J}, \quad (35)$$

$$t_2 = \frac{5\sqrt{2}\pi}{3J} \quad (36)$$

being the real solution with the shortest time.

V. SMOOTH PULSES USING DYNAMICAL INVARIANTS

The relatively long time for the $\frac{\pi}{2}$ X rotation using square pulses is the reason the iSWAP takes $\approx 116/J$. Instead of performing the $\pi/2$ X rotations and X gates using a sequence of square pulses, it is possible to perform smooth controls using the dynamical invariant of the Hamiltonian [19, 20]. Using smooth pulses instead of square pulses is also preferable in practice, due to the limited bandwidth capabilities of arbitrary wave form generators [32, 33] and low-pass filters used to suppress the noise from the surrounding circuitry [34, 35].

In this section it will be shown that using this dynamical invariant approach the iSWAP gate can be implemented in $\approx 19.5/J$ given a tolerance for a small error. A dynamical invariant $I(t)$ obeys Eq. (1). For an $\mathfrak{su}(2)$ Hamiltonian with controls on two Pauli generators, such as Eq. (12) (15), the general form of $I(t)$ is known to be [20, 23]

$$I(t) = \frac{\Omega_{\text{ref}}}{2}(\cos(\gamma)Z + \sin(\gamma)(\sin(\beta)X + \cos(\beta)Y)) \quad (37)$$

where γ and β are the dynamical invariant parameters and Ω_{ref} is an arbitrary constant with units of energy. The $\mathfrak{su}(2)$ generators $Z_{s_1s_2}$ and $X_{s_1s_2}$ are chosen to be equivalent to an X and Z Pauli matrices in Eq. (37). This unconventional choice is made because it later simplifies the relation of γ and β to Ω and J , the Hamiltonian control parameters in H_{s_1,s_2} . Namely, this relation becomes

$$\dot{\gamma} = -J \sin(\beta) \quad (38)$$

$$\Omega - \dot{\beta} = J \cot(\gamma) \cos(\beta) \quad (39)$$

The evolution operator at the final time, $U(t_f)$, can be expressed in the initial and final values of γ , β and the Lewis-Riesenfeld phase α ,

$$U(t_f) = R_Z(\beta(0))R_Y(\gamma(0))R_Z(2\alpha(t_f) - \beta(t_f) + \beta(0))R_Y(\gamma(t_f))R_Z(\beta(t_f)), \quad (40)$$

where $R_A(\theta)$ is a rotation of angle θ around the A -axis.

By choosing $\beta = \arcsin(-\frac{\dot{\gamma}}{J})$ Eq. (38) is always solved since the exchange, J , is constant. Additionally, this means the other Hamiltonian control parameter, Ω , is described by

$$\Omega = \frac{-\ddot{\gamma}}{\sqrt{J^2 - \dot{\gamma}^2}} + \cot(\gamma)\sqrt{J^2 - \dot{\gamma}^2}. \quad (41)$$

The parametrization of Ω in Eq. (41) is equivalent to that found in Ref. [32, 36] where the dynamical invariants were not the focus. Because the goal is to create Z , equivalent to X_{s_1, s_2} , rotations, we simplify the problem by choosing γ to start and end at 0. By additionally setting $|\dot{\gamma}|$ to start and end at J , the evolution operator becomes $R_X(2\alpha(t_f))$. The Lewis-Riesenfeld phase can be expressed in terms of an integral shown from Ref. [23],

$$\alpha(t_f) = \frac{1}{2} \int_0^{t_f} \frac{\cot(\beta)\gamma}{\sin(\gamma)} dt \quad (42)$$

To create an X gate in the H_{++} and H_{--} subspaces defined in Eqs. (12)-(15) requires that $\alpha(t_f)$ be a multiple of $\pi/2$ while a $\pi/2$ X rotation requires that $\alpha(t_f)$ is $\pi/4$, modulo π .

We satisfy the desired conditions $\gamma(0) = \gamma(t_f) = 0$ and $|\dot{\gamma}(0)| = |\dot{\gamma}(t_f)| = J$ by choosing

$$\gamma(t) = \frac{J}{\pi} \sin\left(\frac{\pi t}{t_f}\right) \quad (43)$$

Additionally, the ansatz in Eq. (43) avoid the potential singularities in Eq. (41) at intermediate times. Through numerical optimization an X gate in the H_{++} and H_{--} subspaces was found at $t_f \approx 7.58/J$ which results in the driving amplitude shown in Fig. 3. (The change in sign of the amplitude can be carried out in practice by a π phase slip.) The dynamics in the H_{+-} and H_{-+} spaces can be corrected using an extra square pulse with the method from Sec. IV B 1. The final square pulse has a strength $\Omega \approx 0.272J$ and time $t \approx 6.06/J$. This results in an infidelity of 10^{-8} which is close to the precision of the optimization used. A $\pi/2$ X rotation is found by driving using Eq. 43 with $t_f \approx 8.25/J$ resulting in driving as shown in Fig. 4 and using a final square pulse with $\Omega \approx 1.41J$ and $t \approx 3.63/J$. If these gates are used instead of the square gates the total time for the iSWAP gate would be $t_{\text{iSWAP}} \approx 54.4/J$ instead of $\approx 116/J$ using purely square pulses.

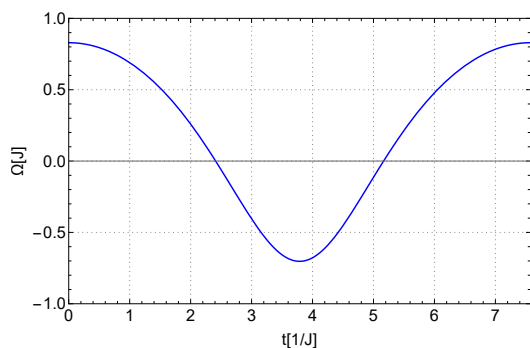


FIG. 3. Pulse shape of the driving strength Ω needed to create an X gate in the H_{++} and H_{--} subspaces.

Performing a $\frac{\pi}{2}$ X rotation using dynamical invariants without the extra square pulse to fix the H_{+-} and H_{-+} subspaces is possible when optimizing a function with

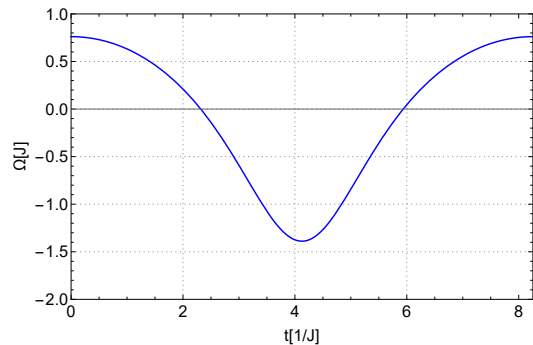


FIG. 4. Pulse shape of the driving strength Ω needed to create a $\pi/2$ X rotation in the H_{++} and H_{--} subspaces.

more parameters. This can be achieved by choosing $\gamma(t)$ to have the ansatz

$$\gamma(t) = \left(\frac{Jt_f}{\pi} - 3c_1\right) \sin\left(\frac{\pi t}{t_f}\right) + c_1 \sin\left(\frac{3\pi t}{t_f}\right). \quad (44)$$

The ansatz in Eq. (44) guarantees that γ starts and ends at 0 and $|\dot{\gamma}|$ starts and ends at J . Additionally, as long as $|\dot{\gamma}| \leq J$ and γ does not reach $n\pi$ when $|\dot{\gamma}| \neq J$ for any integer n a valid solution will be found [32]. A single-shot $\frac{\pi}{2}$ X rotation requires not only $\alpha(t_f) = \pi/2 + n\pi$ as well as $\int_0^{t_f} \Omega(t)dt = \pi/2 + m\pi$ for any integers m and n as long as both are odd or both are even. At $c_1 \approx 0.0537$ and $t_f \approx 0.944/J$ a solution is found that is close to a $\frac{\pi}{2}$ X rotation. The resulting pulse shape for Ω is shown in Fig. 5. It is not an exact solution as it has a trace infidelity $1 - F = 1 - (\text{Tr}(UU_{\text{target}}^\dagger)/8)^2 \approx 1.7 \times 10^{-4}$ where the target evolution operator $U_{\text{target}} = e^{i\frac{\pi}{4}X_2}$. However this method is 20 times faster than using square pulses, taking only $t_f \approx 0.944/J$. The speed-up is partly because this solution enables the use of a higher maximum driving of $\Omega_{\text{max}} \approx 15.3J$ and partly because it does not require an extra square pulse to fix the evolution caused by H_{+-} and H_{-+} . An X gate can be created by doing this pulse shape twice. Using this method to create an iSWAP gate would reduce the time down to $t_{\text{iSWAP}} \approx 13.8/J$ time and would have a trace infidelity of $1 - F \approx 2.7 \times 10^{-3}$.

VI. EXPANDING BEYOND A LINEAR CHAIN

The decomposition of the linear chain Hamiltonian in Eq. (9) into a set of $\mathfrak{su}(2)$ s and $\mathfrak{u}(1)$ s works for a larger number of nearest neighbors as well. An array such as a square lattice, shown in Fig. 6, where every qubit is exchange coupled to its four nearest neighbors will also have a decomposition into $\mathfrak{su}(2)$ s. This is achieved by driving every other qubit in a checkerboard fashion, such that the nearest neighbors of each driven qubit are undriven. In fact, a similar approach works for any lattice configuration as long as the set of nearest neighbors is disjoint with

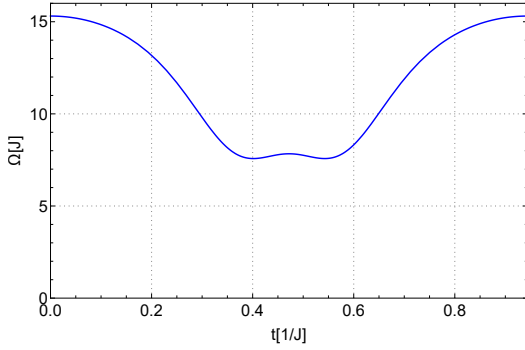


FIG. 5. Pulse shape of the driving strength Ω needed to create a $\pi/2$ X rotation up to a small error.

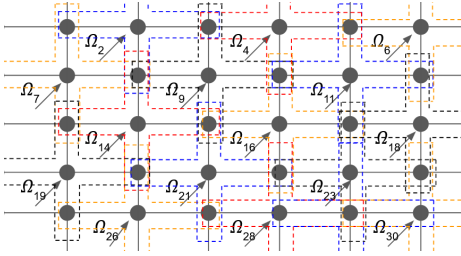


FIG. 6. Schematic representation of the driving on 2D square array of qubits which results in a decomposition of $\mathfrak{su}(2)$ s. The dashed boxes indicate the spin subsets involved in the separate $\mathfrak{su}(2)$ s.

the set of next-nearest neighbors. The number of $\mathfrak{su}(2)$ s will differ depending on the configuration and the relative values of J_{ij} . A lattice point with M connections when driven resonantly will create a possible 2^M $\mathfrak{su}(2)$ s. Some of these might simplify to $\mathfrak{u}(1)$ s such as the case for the linear chain in Sec. III when the coupling J is identical for all nearest neighbor pairs. Generally, though, the problem becomes one of designing a pulse that carries out the desired evolution in each of the $\mathfrak{su}(2)$ s at the same time, as in Sec. IVIV BIV B1. A large number of $\mathfrak{su}(2)$ s then corresponds to having many constraints that the pulse must satisfy.

As the simplest 2D lattice example, the honeycomb lattice has the fewest nearest neighbors, $M = 3$, and the Hamiltonian of a given “Y”-shaped four-site subset resonantly driven on the central site decomposes into 8 $\mathfrak{su}(2)$ s of the form,

$$H_{s_1 s_2 s_3} = (s_1 + s_2 + s_3) \frac{J}{2} Z_{s_1 s_2 s_3} + s_1 s_2 s_3 \frac{\Omega}{2} X_{s_1 s_2 s_3}, \quad (45)$$

with $s_i = \pm$ and $Z_{s_1 s_2 s_3}$ and $X_{s_1 s_2 s_3}$ defined in analogy to Eqs. (16)-(17), where now the central spin has three neighbors instead of two. Fortunately, these 8 $\mathfrak{su}(2)$ s still contain just two unique sets of coefficients up to the signs, corresponding to either all s_i being the same or one of them being different, as in Eqs. (12)-(15). So, there are only two sets of constraints to satisfy for each of the local gates, the same as in Sec. IVIV B. This reduction is only

	$\Omega_1 = \Omega_5$	$t_1 = t_5$	$\Omega_2 = \Omega_4$	$t_2 = t_4$	Ω_3	t_3
$X_{\pi/2}$	0.5 J	9.77/J	0	2.57/J	1.40 J	1.93/J
X_π	0.5 J	9.51/J	0	4.38/J	-2.16 J	1.22/J
$\sqrt{I_{\pi/2}}$	1.74 J	2.38/J	0	3.23/J	1.13 J	2.10/J
$\sqrt{I_\pi}$	1.22 J	3.16/J	0	2.33/J	0.67 J	3.52/J

TABLE II. 5-piece pulse sequence parameters for local rotations of a spin in a honeycomb lattice with fixed couplings. The \sqrt{I} sequences are to be performed twice to produce an identity with the same duration as the corresponding X rotation.

possible for $M < 4$.

Unlike in Sec. IVIV B, none of the $\mathfrak{su}(2)$ s simplify to $\mathfrak{u}(1)$ s, so the pulse design is more tedious. However, using this decomposition and a symmetric five-piece sequence of square pulses one can numerically find rotations of the central spin about X by $\pi/2$ or π , as well as identity operations of the same duration, as given in Table VI. The iSWAP gate can be formed by interspersing these rotations on the central spins of the subsets in between undriven entangling periods just as in Sec. IV. The total time for the whole iSWAP sequence using these pulses is $\approx 195/J$, but these could almost certainly be greatly reduced by using faster smooth pulses instead of the proof-of-principle square pulse sequence above, as in Sec. V. We have not yet carried out this cumbersome calculation.

A square lattice ($M = 4$) with identical couplings driven as in Fig. 6 is more complicated. The Hamiltonian decomposes into 16 $\mathfrak{su}(2)$ s, of which *three* contain a unique set of coefficients modulo the signs. The simple square pulse form of Sec. IVIV B cannot work because there are more constraints than free parameters. Using a longer sequence of square pulses (as we did above for the honeycomb lattice) or reverse-engineering a smooth pulse using dynamical invariants as in Sec. V is necessary, and the numerics become more challenging.

VII. CONCLUSION

In summary, we have used Cartan decomposition and dynamical invariants to create an iSWAP gate in a chain of always-on exchange coupled qubits which can be used for spin shuttling. The Cartan decomposition in the chain of always-on exchange coupled qubits is found by driving every other qubit. This results in sets of four $\mathfrak{su}(2)$ Hamiltonians for every driven qubit. To implement an iSWAP gate in these Hamiltonians only $\frac{\pi}{2}$ X rotations, $\frac{\pi}{2}$ ZZ rotations, and X gates are required if virtual Z gates are possible. Using square pulses and Euler angle decomposition, it was shown that these gates can be implemented. This method of creating an iSWAP gate takes $t_{\text{iSWAP}} \approx 116/J$. To do this faster, a method using the dynamical invariants to create smooth fields to create an iSWAP gate was shown (we note that the obtained dynamical invariants can in principle be used

for other purposes, such as transitionless quantum driving of a single state). This yielded a iSWAP gate in $t_{\text{iSWAP}} \approx 54.4/J$ for an analytical solution or in only $t_{\text{iSWAP}} \approx 13.8/J$ for a numerical solution with an infidelity of 2.7×10^{-3} . The decomposition into $\mathfrak{su}(2)$ s also works for a 2D array of qubits with more than 2 nearest neighbors as long as the set of nearest neighbors is disjoint from the set of next-nearest neighbors. In the case of a honeycomb lattice, we have shown how to perform directed transport of the spin state on the lattice without control of the coupling. For other lattices, solutions

are expected to exist, but exploring the methods to find them is an open task for future research.

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